

Novel Sensors, New Estimation Algorithms and Advanced Controls: Solutions for Improving Highway Vehicle Safety and Mobility

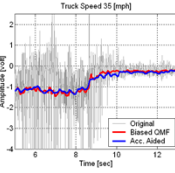
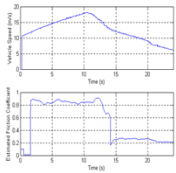
Real Time Estimation of Tire-Road Friction Coefficient



- Goal: Develop an on-board friction measurement system for a snow plow
 - Continuously estimate friction between the tires and the road while the snowplow travels
 - Track and provide estimated friction values to the vehicle operator
 - Automated application of sand, salt and deicing material to the roadway

Vehicle based friction estimation system

- Uses on-board vehicle motion sensors such as GPS, accelerometers, gyroscope and wheel speed
- Tests conducted at skid pad with transition from dry asphalt to icy road



Wheel based friction estimation system

- Uses a small redundant wheel on the snowplow
- Novel system with no actuation and minimal moving parts
- Closed-loop control of applicator for winter road maintenance

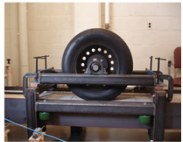


Wireless Tire Sensors for Measurement of Slip Angle, Slip Ratio and Friction Coefficient

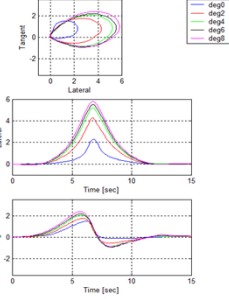
- Development of sensors to measure tangential, radial and lateral tire deformations in the contact patch
- Development of algorithms to estimate slip angle, slip ratio and tire-road friction coefficient from tire deformation measurements



Tire test rig



Tire deformations



Battery-Less Wireless Traffic Sensors

- Novel sensors based on energy harvesting from piezoelectric element embedded in the roadway
- Design
- 1 inch wide beam installed in the lane – does not require battery, power supply or any wiring
 - Data from multiple sensors can be received by a single wireless transceiver located up to 500 feet from sensors



- Advantages over inductive loop detectors
 - Low cost (eventual cost expected to be less than \$100)
 - Easy installation, no wiring
 - No electrical power supply or batteries required
 - Suitable for rural roads

Narrow Tilt-Controlled Commuter Vehicles

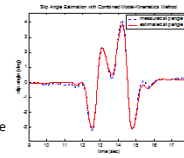


Goal: To develop a traffic and environment friendly commuter vehicle that

- Requires only a half-width lane on the highway
 - 6 feet instead of 12 feet wide
- Provides high fuel economy (100 miles per gallon)
- Is as safe and as easy to drive as a regular passenger sedan
 - Control system keeps the vehicle balanced while driving straight
 - Control system tilts the vehicle into curves while cornering

Observer Design and Fault Diagnostics

- Observer Design for Nonlinear Systems
 - State and unknown input estimation for Lipschitz and bounded Jacobian nonlinear systems
 - Systematic time-varying observer design method for parameter varying systems
- Slip angle estimation for electronic stability control
- Fault Diagnostics
 - NSF CAREER Award
 - Fault detection and identification for nonlinear dynamic systems
 - Fault diagnostics for radar and inter-vehicle measurements



For more information, contact Prof. R. Rajamani, rajamani@me.umn.edu

Nature-Inspired Magnetic Sensors for Accurate Position Measurement

- Sensing Principles
 - Many creatures, including butterflies, newts and dolphins use Earth's magnetic field lines for navigation
 - Likewise, this work seeks to extend the same ideas to measure distances to ferromagnetic objects, exploiting their inherent magnetic fields
 - Example of a magnetic field model for a ferromagnetic object
- Imminent Collision Prediction
 - Use of adaptive estimation algorithms and redundant magnetic sensors to eliminate need for calibration
 - Sample data with two different vehicles
- Non-Intrusive Measurement of Piston Position
 - Applications to hydraulic, pneumatic and IC engine cylinders
 - Adaptive algorithms, auto calibration and automatic disturbance rejection

$$B_x \cong \frac{p}{x_A} + q$$

